SimplyDroid: Efficient Event Sequence Simplification for Android Application*

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Abstract—To ensure the quality of Android applications, many automatic test case generation techniques have been proposed. Among them, the Monkey fuzz testing tool and its variants are simple, effective and widely applicable. However, one major drawback of those Monkey tools is that they often generate many events in a failure-inducing input trace, which makes the followup debugging activities hard to apply. It is desirable to simplify or reduce the input event sequence while triggering the same failure. In this paper, we propose an efficient event trace representation and the SimplyDroid tool with three hierarchical delta-debugging algorithms each operating on this trace representation to simplify crash traces. We have evaluated SimplyDroid on a suite of real-life Android applications with 92 crash traces. The empirical result shows that our new algorithms in SimplyDroid are both efficient and effective in reducing these event traces.

Index Terms—Test case reduction, delta debugging, event sequence reduction, Android

I. INTRODUCTION

The mobile Internet industry has witnessed an explosive growth in recent years. Both the number and the complexity of mobile applications have increased rapidly. According to Gartner [33], the Android OS has taken 87.8% of the smart phone market share in the 3rd quarter of 2016. In Google Play [34], there are more than 2.6 million Android applications [38].

To increase the satisfaction of end-users, mobile application developers must improve the quality of their applications. Mobile testing is one important measure to achieve this goal. Different kinds of testing techniques [8] have been proposed to test Android applications, including fuzz testing, GUI traversalbased testing [3][17], and search-based testing [18]. Fuzz testing is represented by the family of Monkey tools, which includes the built-in Monkey tool of Android OS and its improved versions by third party. Owing to their simplicity, effectiveness, and wide applicability, the improved monkey tools are widely adopted by cloud-based mobile testing platforms [35][39][41].

A major limitation of these fuzz testing techniques is that they often generate a large number of input events before triggering a failure, which makes follow-up debugging tasks

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hard to apply. In such scenarios, simplifying input event sequence that triggers the same failure is desirable.

Delta debugging (DD) [27] has been applied to perform such test input reductions on traditional applications, Web applications, and compilers, etc. There are also research works on reducing input event sequences for Android applications with the emphasis on handling execution non-determinism based on the idea of DD [9]. Nonetheless, in general, DD techniques are slow to generate the reduced input. The problem with the DD strategy is that its partition strategy is unaware of the presence of interaction sessions of input events with end users, which may lead to large number of unsuccessful trials (i.e., fail to trigger failure) in the reduction process.

Hierarchical Delta Debugging [19] improves the efficiency of DD by revealing the hierarchical structures of test cases and applying DD according to such structures. We observe that an Android input event sequence can be structured hierarchically based on interaction sessions and sub-session with users.

Our insight into the events trace reduction problem is that a long input event sequence often contains sub-sequences representing small interactive sessions with the end users. These sessions of events forms a natural boundary for reduction as they can often be reduced together with high probability. We further observe that the relationship of input events is reflected in the hierarchical relationship of their corresponding GUI states. Thus, we seek to find the hierarchical relationships between input events by building and analyzing the GUI state hierarchy tree as trace representation.

Based on the trace representation, we further propose an input event sequence simplification tool SimplyDroid, which contains a family of three test case reduction algorithms based on the notion of hierarchical delta debugging coined as Hierarchical Delta Debugging (HDD), Balanced Hierarchical Delta Debugging (BHDD), and Local Hierarchical Delta Debugging (LHDD) each operating on the above trace representation. The HDD algorithm is an adaption of the existing notion of hierarchical delta debugging to show the applicability of our trace representation. Both BHDD and LHDD are our new HDD algorithms that use the structural property of the trace representation to improve the reduction efficiency without significant loss of reduction effectiveness.

We have used 92 input traces with crash occurrences from 8 real-life Android applications with real and seeded faults to evaluate the SimplyDroid tool. The experimental results show

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that all the three techniques have improved reduction efficiency over the classic DD technique without loss of effectiveness. Furthermore, LHDD is significantly more efficient than DD, HDD and BHDD, which makes it competitive to apply.

The contribution of this paper is three-fold. First, it presents a novel GUI state hierarchy tree representation to model an Android input event trace. Second, it proposes the first family of efficient HDD algorithms for simplifying Android input event traces. Third, it reports the first comprehensive experiment on 92 crash traces of 8 real-world Android applications that evaluates the effectiveness and efficiency of our family of HDD algorithms and trace representation.

The organization of the remaining sections is as follows. In Section II, we present a motivating example to illustrate our key ideas. In Section III, we present our tool SimplyDroid¹ as well as the family of input sequence reduction algorithms. Section IV reports a comprehensive experimental study, in which we have evaluated the effectiveness and efficiency of our family of HDD algorithms operating on our trace representation, followed by the related work in Section V. Finally, we conclude our work in Section VI.

II. MOTIVATING EXAMPLE

This section presents a motivating example of our work.

A. GUI State Hierarchy Tree as Trace Representation

To understand the hierarchical structure of GUI input events, we have to build a partial GUI state hierarchy tree and map the input events to it. Here "partial" means the GUI hierarchy tree only reflects those parts of the GUI hierarchy related to the current input event sequence for simplification. Fig. 1 shows the GUI state hierarchy tree built from a real crash trace from the Android application *DalvikExplorer*.

When building the GUI state hierarchy tree, we use the hierarchical relationship of GUI states to identify the hierarchical relationship of their corresponding events. In this state hierarchy tree, each node with number i not only represents the event i in the crash trace, but also represents the GUI state before processing the event i. An edge in the GUI state hierarchy tree represents the parent-child (hierarchical) relationship between the two corresponding GUI states.

If a new node n with a state different from any nodes on the path from the root node to its previous node, then the node n is defined as a child node of its previous node; otherwise, the node n is defined as a new (and right) sibling node of the equivalent node having the same state as n. In Fig. 1, within the state hierarchy tree, we use the same color to represent equivalent states (sibling) and the last node without any index to stand for state "crash". With the GUI hierarchy tree construction process, new events will always grow at the rightmost sub-tree. Thus, the crash node (i.e., the last event of the event sequence) is always the rightmost node at the bottom level of the rightmost sub-tree of the whole tree. Furthermore, the parent and the ancestors of the crash node are always the *last* nodes in their corresponding levels.

We have built an enhanced Monkey tool to log the application GUI states during testing. The definition of GUI state can have different granularities. In the current version of SimplyDroid, we use an Activity ID to represent a GUI state, which is a lightweight solution. Using a finer level of GUI state (e.g., GUI structure) definition may lead to different reduction results, whose tradeoff is interesting to explore in the future.

Therefore, our crash traces contain not only the sequence of input events but also the corresponding GUI states. More specifically, our crash trace of events is in the form $\langle e_1, e_2, ..., e_n \rangle$, and it corresponds to the GUI state trace $\langle s_1, s_2, ..., s_{n-1}, s_n, crash state \rangle$. Upon receiving event e_i , the state s_i transits to s_{i+1} .

The GUI state hierarchy tree is constructed as follows. For each state s_i and event e_i with the same number i, a new node nis constructed. Then node n is compared with each node (state) m from root to its previous node s_{i-1} in turn. If s_i is equal to any node m, node n is added as a sibling node of m. Otherwise, n is added as a child node of node s_{i-1} . The tree construction algorithm will be presented in Section III.



B. The Reduction Process of Classic DD

The Delta Debugging (DD) algorithm makes no use of the hierarchical relationships of GUI states [27]. It partitions an input event sequence into subsequences with equal size, and performs reduction with increasingly finer granularity. For the exemplified crash trace of length 36, in our experiment, the DD algorithm used 38 trial executions by spending 3 minutes and 15 seconds before getting the final reduced test input sequence $\langle 1, 22, 23, 36 \rangle$. We observed that many of these 38 trial executions generated invalid traces, which wasted efforts.

C. The Reduction Process of HDD



The idea of HDD is to perform the reduction from a higher level to a lower level on a GUI state hierarchy tree. In this way, the sub-trees of a node can be reduced together, leading to

¹ The SimplyDroid tool is open source at https://github.com/gongbell/SimplyDroid

higher reduction efficiency. Within each level, the reduction strategy of HDD is similar to DD. Fig. 2 shows the reduction attempts of HDD within level 1. While processing level 1, HDD equally partitions the node set (2, 7, 17, 18, 21, 22) shown in Fig. 1 into two parts (2, 7, 17) and (18, 21, 22). It tries to remove one part or the other. As a result, the result for the first round of reduction is shown in Fig. 2(a). We can see that those nodes (2,7, 17) and their sub-trees are all eliminated in one round. Then the node set (18, 21, 22) becomes the input for the next iteration of reduction. This node set is again partitioned into two parts (18, 21) and (22) for reduction. The result for the second round of reduction is shown in Fig. 2(b). The reduction at level 1 stops because there is only one node numbered 22 remained. Then the reduction at levels 2 and 3 continue iteratively. Finally, HDD used 6 trial executions by spending 64 seconds to get the same reduction result $\langle 1, 22, 23, 36 \rangle$ as DD. We can see from the reduction process that HDD is more efficient than DD.

D. The Reduction Process of BHDD

BHDD is based on the insight that many GUI state hierarchy trees in real-world scenarios are imbalanced: sub-trees with more nodes tend to stay at one side. These trees may make HDD to spend more execution trails on reducing small node sets. BHDD takes the size of whole sub-tree rooted at each node into consideration, and thus has the potential to reduce more nodes in each round of execution trial than HDD.

As shown in Fig. 3, we label the size of the sub-tree for each node at level 1. The partition strategy of BHDD tries to make the total number of nodes in each partition as close as possible. Thus, the first round of partition for BHDD generates node sets (2, 7, 17, 18) and (21, 22). The former has a total of 19 nodes and the latter has a total of 16 nodes. In this way, for an imbalanced tree, BHDD may reduce more events in each round. For the example trace, BHDD used 43 seconds with 6 trial executions to get the same reduction result as DD.



Fig. 3 Partition strategy of BHDD

E. The Reduction Process of LHDD

As discussed in Section II A, the parent and the ancestors of the crash node are always the *last* nodes (e.g., node 22 and 23) in their corresponding levels. We can see from the GUI hierarchy tree of the example that these ancestor nodes of the crash node (e.g., node 22 and 23) are critical because at these nodes, the application under test transits to the next level of GUI state closer to the crash node. Based on this observation, the LHDD algorithm adopts a heuristic: reducing the sequence of events as long as the transition from *the last node of one level* to the *first node of its next level* is preserved. For the exemplified GUI tree in Fig. 1, we need only to check whether the transition $\langle 22, 23 \rangle$ is successful at (blue) level 1 (Fig. 4(b)) and the transition $\langle 23, 24 \rangle$ is successful at (orange) level 2. At the bottom level, LHDD checks for crash occurrence.

In this way, we effectively convert the reduction process from a global optimization problem into a "partial" local optimization problem. By "local", we mean that the reduction process needs not check the sub-tree of the last node, and by "partial" we mean that the subtree of nodes other than the last node should still be checked. For example, when reducing at level 1 (blue nodes), LHDD does not include the subtree rooted at node 22 for checking (i.e., local), but includes the subtrees rooted at 2, 17 and 18 for checking (i.e. partial local). In our experience, the subtree of the last node is often large in size. In such scenarios, intuitively, LHDD saves a lot of time.

To further optimize the local reduction process, LHDD adopts another heuristic before performing the DD reduction at each level. Since the reduced event sequence at current level must include the last node, it incrementally selects nodes (events) with number equal to power of 2 from the last node to front for trial execution and stops when it finds the first subsequence of events that can still reach the first node in the next level. As shown in Fig. 4(a), the pre-selection process will try event sequence $\langle 22 \rangle$, $\langle 21, 22 \rangle$, and $\langle 17, 18, 19, 20, 21, 22 \rangle$ in turn until the event sequence is accepted by the local reduction criteria. Finally, LHDD used only 16 seconds with 4 trial executions to get the same reduction result, which is much more efficient than the previous three DD algorithms.

III. OUR EFFICIENT EVENT TRACE REDUCTION FRAMEWORK

In this section, we first present the overall design of our event trace reduction system. Then we present three test case reduction algorithms: HDD, IHDD, and LHDD.



Fig. 4 Pre-selection and local reduction strategy of LHDD



Fig. 5 Design of SimplyDroid

A. Design of SimplyDroid

The overall design of *SimplyDroid* is shown in Fig. 5. The input of *SimplyDroid* is the original test case (i.e., the original crash trace), while the output is a finally reduced test case. The *SimplyDroid* tool consists of 3 cooperating modules (colored blue): the test case reduction engine, the result checker, and the enhanced Monkey with application state logger. The test case reduction engine is the core of the SimplyDroid tool, which realizes the sets of test case reduction algorithms.

The reduction process is iterative, where the test case reduction engine repeatedly sends reduced Monkey events to the application under test. The enhanced monkey in turn sends the inputs in the script to the application under test. We also enhanced Monkey to record the state of the application (i.e., Activity ID) upon sending each event. At the end of a test script execution, the result checker checks the results by comparing exception messages and the stack traces outputted by Monkey. Then, the test results and the GUI state log is feedback to the reduction engine to continue the delta debugging cycle. Finally, the reduced test case is outputted.

B. Building GUI State Hierarchy Tree

As shown in Table 1, the algorithm builds the GUI state hierarchy tree from the crash trace containing the input events and states. As discussed in Section II, the crash trace of states is in the form $\langle s_1, s_2, ..., s_n, crash state \rangle$ where s_i represents states. Note there is a corresponding events trace $\langle e_1, e_2, ..., e_n \rangle$ where each event e_i triggers the transition from state s_i to s_{i+1} . The algorithm builds a new node for each state s_i (line 1 to 3). Then it is compared with the nodes (states) from its previous node s_{i-1} to the root node (line 4 to 11). If s_i is equal to any node, it is added as a sibling node to it. Otherwise, it is added as a child node of its previous node (line 12 & 13).

TABLE 1. THE GUI HIERARCHY TREE CONSTRUCTION ALGORITHM
procedure build(S)
Input S: the sequences of activity state logged.
Output r : the root node of GUI tree built.
begin
1 $n_0 = \text{new Node}() //n_0$ is an empty node
2 for($i: 1$ to length(S)) {
3 $n_i = \text{new node}(s_i)$ //the state of node n_i is s_i
4 $n_s = n_{i-1}$ //start comparison from previous node
5 while $(n_s != n_0)$ {
6 if $(n_i.state == n_s.state)$ {//find a node with same state as n_i
7 set n_i as a sibling node of n_s
8 break
9 }
10 $n_s = n_s$. parent //walk up the tree,
11 } //end while
12 if $(n_s == n_0)$ { //no node in the path to root have same state
13 set n_i as a child node of n_{i-1}
14 } //end if
15 } //end for
16 return n_0 //return the root node
end

C. Hierarchical Delta Debugging Algorithm (HDD)

As shown in Table 2, the HDD algorithm is a realization of the idea of existing hierarchical delta debugging but operating on our tree-based representation of a trace.

TABLE 2 THE HDD ALGORITHM

```
procedure hdd(\overline{E, r})
      Input E : the sequence of events logged.
      Input r: the root node of the GUI state hierarchy tree.
      Output E_r: the simplified event sequence.
      begin
        M.add(r) //M is a global vector storing the reduced events
1
2
3
        nodeseq = empty //nodseq stores the reduced nodes at each level
        N = empty // N stores the sequence of nodes in next level
4
5
         add to N the child nodes of each node in M
         do {
6
            i\hat{f}(N is not empty) {
7
              inlevel hdd(N, 2) //reduction in current level
8
              for(each node n_i in N) {//M now contains the reduced events
9
                 if (M.contain(n_i)) (//update nodeseq with M)
10
                   nodeseq.insert(ni)
11
12
                 else {
13
                   remove node n_i and its subtree from the tree rooted at r}
               } //end for
14
15
              } // end if (N is not empty )
             N.clear() //clear N to be empty
16
             add to N the child nodes of each node in M //update N
17
           }while (N is not empty);
         //note Er is updated in checkEvents on triggering bug
18
         return Er
19
      end
      procedure inlevel hdd(N<sub>0</sub>, p)
      Input N_0: the sequence of nodes need to simplify at current level
      Input p: the number of partition in this simplification.
      begin
20
         if( length( N_0 ) < p )
21
22
            return
         //partition N_0 into p subsequences N_1, N_2, \dots N_p
23
         [N_1, N_2, \dots, N_p] = partition(N_0, p)
24
25
         evtseq = nodes2events( nodeseq ) //map nodes (states) to events
         for( each node n_i in group N_p) { //test N_p first
26
27
28
           evtseq.insert(eventsInSubTree(n<sub>i</sub>)) //inserts events in subtree
         } //end for
         if(checkEvents(evtseq)) { //execute evtseq for checking
29
            M = N_{\rm p} //record current reduction result
30
            inlevel_hdd(N<sub>p</sub>, 2) //continue finer reduction
31
            return //successful reduction from N<sub>p</sub>, return
32
33
         for( i : p-1 to 1 ) {
            //check the complement of the other p-1 partition
34
            evtseq = nodes2events( nodeseq )
35
            for (each node n_i in N_i to N_p except N_i ) {
36
              evtseq.insert(eventsInSubTree(n<sub>i</sub>))
37
38
            if( checkEvents( evtseq ) ) {
39
              M = \text{merge}(N_I \text{ to } N_p \text{ except } N_i)
40
              inlevel_hdd(M, p-1)
41
              return; //successful reduction from complements
42
         } //end for
         //fail at current granularity, reduction at finer granularity
43
         inlevel_hdd (N_{p}, min( 2*p, length( N_p ) ) )
44
         return
45
      end
46
      procedure checkEvents(E_{\theta})
47
      Input E_0: the sequence of events need to execute on the application.
48
      Output res : whether this sequence can reproduce the crash.
49
      begin
50
            if E_0 can trigger crash on execution {
51
               E_r = E_0 //update E_r on successful triggering crash
52
              return true } // end if
53
            return false //Events cannot trigger crash
54
      end
```

This algorithm starts by invoking hdd(). Owing to one-one correspondences between input events and nodes (states) in the tree, the algorithm simplifies the nodes (states) level by level from top to bottom (line 1 to 17). Within each level, the in-level node simplification procedure *inlevel hdd()* is called (line 7). M is a global vector storing the current successfully reduced events, which is updated in *inlevel hdd()* (line 29 and 39). The *nodseq* stores the reduced nodes at current level and is updated by M(line 10). And, N stores the next level of nodes for reduction. The inlevel hdd() realizes the idea of hierarchical delta debugging within one level until a simplest node sequence is found. It partitions the event sequences (line 23), checks the last partition, and performs recursive reduction if successful (line 30). Otherwise, it tries to reduce the complement of other partitions (line 33 to 41) with recursive calls. If it still fails, it performs finer level reduction (line 44). The procedure *checkEvents()* is responsible for execute event sequences, check whether the crash is triggered and update E_r , the final simplified event sequence (line 46 to 54).

There are three subroutines whose implementation is omitted for brevity, which we explain as follows: (1) *partition()* (line 23), whose function is to partition node sequence into subsequences with equal number of nodes. (2) nodes2events() (line 24, 34) maps the sequence of nodes to the corresponding sequence of events. (3) eventsInSubTree() (line 26, 36), whose function is to return all events in the subtree of a node.

D. Balanced Hierarchical Delta Debugging Algorithm (BHDD)

The algorithm of BHDD optimizes the HDD algorithm by changing the subroutine partition() (i.e., line 23 of HDD algorithm). The *partition()* of BHDD is to divide node sequence in the current level into partitions with equal number of nodes by counting the number of nodes in their sub-trees. We omit its detailed implementation for brevity.

E. Layed Hierarchical Delta Debugging Algorithm (LHDD)

As shown in Table 3, the algorithm *lhdd()* is based on *hdd()* except with two optimizations. The first optimization is to add a process of pre-selection (line 7 to 22), within which more nodes are selected until the selected sequence of events that can trigger a transition to next level of Activity is found. The second optimization is to only checks the successful transition from the last node in the local level to the first node in the next level of Activity in checkEvents(). This saves the execution of the events in the subtree of the last node.

The procedure *inlevel hdd()* of LHDD is the same as that of HDD algorithm, so we omit it for brevity. However, there are some procedures called in *inlevel hdd()* that is changed for LHDD algorithm, which we detail them here. First, the function eventsInSubTree() for LHDD is the same as that for HDD except that if a node is the last node, it adds only the node itself without adding events in its subtree. Second, the function *partition()* for LHDD is the same as that of BHDD by considering of number of nodes of the subtrees, except that the size of the last node in N is counted as 1. The difference in these two procedures essentially reflects the local reduction logic: the sub-tree of the last node in the current level is not considered during reduction.

TABLE 3 THE LHDD ALGORITHM

```
procedure lhdd(E, r)
      Input E: the sequence of events logged.
      Input r: the root node of the GUI state hierarchy tree.
      Output E_r: the simplified event sequence.
      begin
1
         M.add(r) //M is a global vector storing the reduced events
2
3
         nodeseq = empty //nodseq stores the reduced nodes at each level
         N = empty // N stores the sequence of nodes in next level
4
5
6
         add to N the child nodes of each node in M
         do {
              if (N is not empty) {
7
              preLen = 1 //perform preselection, start at 1
8
               // get the current preselected node sequence N_s
9
              N_s = N[\text{length}(N) - \text{preLen}, \text{length}(N) - 1]
10
              while( preLen < length(N) ) {
                 evtseq = nodes2events (nodeseq) // to event sequence
11
12
                 for( each node n_i in group N_s) {
13
                    //add sub-tree of selected nodes except the last node
14
                   evtseq.insert(eventsInSubTree(n_i))
                   } //end for
15
                 if( checkEvents( evtseq ) ) {//preselection is successful
16
                     break; //exit preselection
17
18
                 else { //try pre-selection with double size
19
                   preLen = min(2* preLen, length(N))
                   N_s = N[\text{length}(N) - \text{preLen}, \text{length}(N) - 1]
20
21
22
              } // end of while, preselections stops
23
             inlevel_hdd(N<sub>s</sub>, 2) //performing in level reduction
23
24
25
             for( each node n_i in N ) {
               if (M.contain(n_i)) {//update nodseq with M
26
                  nodeseq.insert(n_i)
27
28
                 else {
29
                  remove node n and its subtree from GUI tree rooted at r
30
31
              } //end for
32
            } //end if (N is not empty)
33
            N.clear() //clear N to be empty
34
            add to N the child nodes of each node in M //update N
35
         }while( N is not empty ); //reduce at all levels
36
         //E_r is updated in checkEvents on triggering bug
37
         return Er
38
      end
40
      procedure checkEvents(E_{\theta})
41
      Input E_0: the sequence of event need to execute in the application.
42
      Output res : whether this sequence can trigger the crash at last level
      or transit to next activity successfully at middle level
43
      begin
44
         if (E_0 \text{ contains the last event of } E) \{ //\text{last level, testing for crash} \}
45
            if E_0 can trigger crash {
               E_r = E_0 / \tilde{\text{update } E_r} with the sequence E_0
46
47
               return true;
48
              }
49
50
         else { //not last level, testing for transition
51
             If E_0 can transit to the first node in the next level of Activity
52
                return true; }
53
         return false; //events can neither trigger crash nor transition
54
```

Finally, the procedure *checkEvents()* called in both *lhdd()* and inlevel hdd() is also changed (line 40 to 54), which differentiates local check at intermediate levels and the final check in the last level. For the local check, the algorithm only checks the successful transition to the next Activity. For the final check in the last level, the algorithm checks whether a crash is triggered.

end

Subject	Subject Description	Program	Android	Fault	Daviaa	Execution Turne	Number of	Crash Trace
Subject	Subject Description	Version	Version	Туре	Device	Exception Type	crash traces	Length
Yahtzee	Game	1.1	2.3.3	Mutant	Mi5	ArithmeticException	17	100-214
K9mail	Mail	5	2.3.3	Mutant	Mi5	NullPointerException	23	150-621
DalvikExplorer	System information	3.4	4.1.2	Real	Mi1	ActivityNotFound &	11	36-1525
-	viewer					OutOIMemoryError		
WeightChart	Weight recorder	1.0.4	2.3.3	Real	Mi1	ActivityNotFound	8	16-765
Ringdroid	Ringtone editor	2.6	4.1.2	Real	Mi1	RuntimeException	6	314-885
Tippy	Calculator	1.1.3	2.3.3	Mutant	Mi5	ArithmeticException	9	31-162
SyncMyPic	Photo synchronizer	0.15	2.3.3	Mutant	Mi5	ArithmeticException	8	27-462
WhoHasMyStuff	Item lending helper	1.0.7	4.4.2	Mutant	Mi5	RuntimeException	10	50-679

TABLE 4 SUBJECT PROGRAMS

IV. EXPERIMENT AND RESULTS ANALYSIS

This section presents our experiment and data analysis.

A. Research Questions

RQ1: Are HDD, BHDD, and LHDD effective to reduce the size of Android input event sequence?

RQ2: Are HDD, BHDD, and LHDD efficient when performing test case reduction?

RQ3: If LHDD is efficient, which of the two optimizations contributes more to its performance improvement.

B. Experimental Setup

We used a Lenovo laptop V4400 as our testing host. The laptop was equipped with Intel i7 4702 and 16GB memory. The operating system was Windows 10 and the Integrated Development Environment was Eclipse. We used the Monkey tool as our testing engine. On the phone model Mi1 the interval between sending two events was set as 500ms and on Mi5 the interval was set as 800ms to make sure that there was enough time for each event to be processed.

C. Subject Program and Crash Traces

We have selected 8 real-life subject programs for our experimental study. The descriptive statistics of the 8 subject programs is summarized in Table 4. We have listed the program name, a brief description of the application, the application version, the Android OS version, the type of fault within the application, the device hardware model used to run the tests, the types of exceptions captured upon crash, the number of crash traces for each application, and the range of the length of the traces in the table. For example, *Yahtzee* was a mobile game application whose program version is *1.1*. The application was running on Mi5 phone with Android OS version 2.3.3. We injected mutant faults within the application to generate 17 crashes of type *ArithmeticException*, and the number of events within the crash trace ranges from 100 to 214. The other subjects can be interpreted similarly.

All the 8 subjects were all real-life mobile application that had evolved for many years. Furthermore, the released versions were often quite stable while unstable commit versions were often hard to acquire. As a result, finding crash traces in application releases with Monkey was not an easy task. For DalvikExplorer, WeightChart, and Ringdroid, we were lucky enough to find 25 crash traces with real faults. For the other 5 subjects, we had to manually create mutants by injecting faults frequently found in mobile applications. We inserted, removed or modified statements to inject faults. We got another 95 crash traces from the mutant programs.

Our algorithm only worked on deterministic traces, so we examined these 120 crash traces to check whether they can replay stably. We manually executed each crash trace 3 times. Then we compared their exception messages and stack traces in the output to confirm reproducibility. We removed 19 traces, which cannot be replayed by Monkey stably due to non-determinism in its execution. We removed a subject called *Sanity* and its 7 crash traces because replaying it stably requires resetting its data before each execution, which was not supported by the current implementation of SimplyDroid. We removed 2 versions of *WhoHasMyStuff* because the interaction with the application may sometimes activate the soft input keyboard, which changed the layout of the GUI. As a result, the coordinate-sensitive Monkey cannot replay them. Finally, the 92 crash traces left were all used in our data analysis.

To facilitate identification of the GUI state hierarchy, we had also enhanced Monkey tool to log the application GUI states (i.e., Activity ID in this work) during testing. Therefore, our crash traces contained not only the sequence of input events but also their corresponding GUI states.

D. Experimental Procedure

We also realized the classic Delta-Debugging (DD) algorithm as a benchmarking technique for comparison. We performed test case reduction on all the 92 crash traces with DD, HDD, BHDD, and LHDD algorithms. We logged the size of the reduced test cases as well as the time for reduction for each technique on each trace. Since there are two major optimizations in the LHDD algorithm (i.e., the pre-selection and the local reduction), we wonder which optimization contributes more in its performance improvement. So we turned off the pre-selection optimization only) to form a new technique LHDD-NoPre for comparison with LHDD. We also used LHDD-NoPre to perform test case reduction on the 92 crash traces and log their reduction results.

E. Experimental Results and Analysis

In this section, we present our experimentation results followed by detailed results analysis for each research question.

1) Answering RQ1: In this section, we would like to know whether our proposed HDD techniques are effective to reduce the size of Android input event sequence.

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Subjects								Ya	htz	ee																		K	9m	iail												Dal	lvik	Ex	plor	er
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Original	168	196	153	3214	131	100	101	110	121	121	126	128	3111	134	112	3107	711	.017	115	658	721	662:	126	918	419	327	521	636	626	6217	261	272	215	5220	202	154	216	150	269	180	36	75	117	307	7950	1525
DD	8	7	7	8	7	7	9	7	7	7	9	7	8	7	7	7	7	6	5	7	4	4	4	4	7	5	4	5	5	8	5	5	6	5	4	4	5	7	8	5	4	4	4	4	4	4
HDD	7	9	10	9	8	8	8	7	8	9	7	10	9	9	7	10) 7	' 10) 6	5	7	5	5	4	8	6	6	7	5	9	5	8	6	4	8	4	6	4	10	7	4	4	4	4	4	4
BHDD	8	9	10	8 (8	8	7	7	8	8	8	10	11	10	8	8	8	3 7	5	5	7	5	5	4	12	2 5	7	6	4	11	6	6	6	4	5	5	5	6	9	10	4	4	4	4	4	4
LHDD	7	8	7	8	7	8	7	7	8	8	8	7	8	7	7	9	8	3 7	7	6	6	9	6	6 4	6	6	5	17	6	11	10	9	6	5	5	5	9	6	7	13	4	4	4	4	4	4
LHDD -NoPre	7	8	7	8	7	9	7	7	7	7	7	7	7	7	7	7	7	10	9	5	6	8	7	6	6	6	4	15	13	312	8	8	5	4	4	4	11	4	7	12	4	4	4	4	4	4
Subjects	Da	lvik	Ex	plo	rer			We	igh	tCł	har	t			F	Ring	Jdr	oid	1		1	_		Tip	ру		1				Sy	/ncl	My	Pic		L			W	/ho	На	sN	lyS	tuf	f	
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Subjects No. Original	Da 47 1359	Ivik 48	Ex 49	plo 50	rer 5294	52	53 46	We 54	igh 55 514	tCł 56 239	nar 57	t 58 448	59 220	60	F 61	62	idr 263	oid 3 64	65 670	5 66	6 76	7 68 6 63	3 69 3 31	Tip 9 7(1 10	py) 7 [.] 212	1 72 916	2 7 3 2 46	3 7 4 6 99	75	76	Sy 77	/ncl 78	My 79	Pic 80	81 27	82	83 132	84 78	W 85	/ho 86	Ha 87	sN 88	1yS 889	tuf 90 7679	f 9 91	92 231
Subjects No. Original DD	Da 47 1359 4	Ivik 48 397 4	Ex 49 404 9	plo 50 1265 4	rer 51	52 16 9	53 46 5	We 54 521 5	igh 55 514 9	tCł 56 239 5	nar 57 765 5	t 58 448 5	59 220 5	60 885 8	F 61 544! 8	8ing 62 550 7	101 2 6: 031 7	oid 3 64 464	65 70 7	5 66 6 70 4	6 76 4	7 68 5 63 4	369 31 4	Tip 9 7(1 10	py) 7 [.] 212 4	1 72 916 4	2 7 3 2 46 4	3 74 5 99 4	45 45	76 426 4	Sy 77 89 4	/ncl 78 154 4	My 79 177 2	Pic 80 7462 4	81 27 4	82 44 2	83 132 6	84 ⁷⁸	N 85 306 5	/ho 86 353 6	Ha 87 472 6	sN 88 50	1yS 89 217 6	tuf 90 7679 6	f 91 9149 5	92 231 6
Subjects No. Original DD HDD	Da 47 1359 4 4	lvik 48 397 4 4	Ex 49 404 9 11	plo 50 1265 4 4	rer 51 294 4 4	52 16 9 7	53 46 5 9	We 54 521 5 8	igh 55 ⁵¹⁴ 9	tCh 56 239 5 7	nar 57 765 5 8	t 58 448 5 19	59 220 5 7	60 885 8 7	F 61 544 8 7	8ing 62 550 7 7	1dr 63 31 7	oid 3 64 4 64 7 7 7 7	65 70 7 7	5 66 6 70 4	67 76 4	7 68 63 4 6	3 69 3 31 4 4	Tip 9 7(1 10 4 • 4	py) 7 [.] 212 4	1 72 916 4	2 73 2 40 4	3 74 5 99 4 4	45 45 4	5 76	Sy 77 89 4 4	/ncl 78 154 4 4	My 79 177 2 6	Pic 80 7462 4 9	81 27 4 4	82 44 2 3	83 132 6 6	84 ⁷⁸ 6	W 85 306 5 5	/ho 86 353 6 7	Ha 87 472 6 6	sN 88 50 5	1yS 89 217 6 6	tuf 90 679 6	f 91 149 5 5	92 231 6 6
Subjects No. Original DD HDD BHDD	Da 47 1359 4 4 4	Ivik 48 397 4 4 4	Ex 49 404 9 11	plo 50 1265 4 4 4	rer 51 294 4 4 4	52 16 9 7 9	53 46 5 9 5	We 54 521 5 8 8	igh 55 514 9 8 8	tCh 239 5 7 7	nar 57 765 8 8	t 58 448 5 19 18	59 220 5 7 7	60 885 8 7 7	F 61 544 8 7 7	8ing 62 550 7 7 7	10 2 6 3 1 7 7 7	oid 3 64 4 64 7 7 7 7 7 7	65 70 7 7 7	5 66 6 70 4 4 4	676 76 4 4	7 68 5 63 6 4 6 6	3 69 3 31 4 4 4	Tip 9 7(1 10 4 4 4	py 212 4 4	1 72 916 4 4	2 73 2 46 4 4	3 74 5 99 4 4 4	45 45 4 4 4	5 76 420 4 5 5	Sy 77 89 4 4 4	/ncl 78 154 4 4 4	My 79 177 2 6 6	Pic 80 7462 4 9 9	81 27 4 4 4	82 44 2 3	83 132 6 6 6	84 ⁷⁸ 6 6	W 85 306 5 5 5	/ho 86 353 6 7 6	Ha 87 472 6 6	sN 88 50 5 5 5	lyS 889 217 6 6 6	tuf 90 7679 6 7	f 9149 5 5 5	92 231 6 6 6
Subjects No. Original DD HDD BHDD LHDD	Dal 47 1359 4 4 4 4	Ivik 48 397 4 4 4 4 4	Ex 49 404 9 11 11	plo 50 1265 4 4 4 4 8 4	rer 51 294 4 4 4 4	52 16 9 7 9 5	53 46 5 9 5 6	We 54 521 5 8 8 8	igh 55 514 9 8 8 9	tCh 56 239 5 7 7 7	nar 57 765 5 8 8 8	t 58 448 5 19 18 14	59 220 5 7 7 9	60 885 8 7 7 7 7	F 61 5449 8 7 7 7 7	8ing 62 550 7 7 7 7 7	ydr 6; 31 7 7 7 6	oid 3 64 4 64 7 7 7 7 7 7 8 8	65 70 7 7 7 7	5 66 6 70 4 4 4 4	67 76 4 4 4	7 68 5 63 4 6 6 6	- 3 69 3 31 4 4 4 4	Tip 9 7(1 10 4 4 4	py 212 4 4 4	1 72 916 4 4 4 4	2 7 (2 4 (4 4 4 4	3 74 5 99 4 4 4 4 4 4	45 45 4 4 4 4 4	76 420 4 5 5 5	Sy 77 89 4 4 4 4	/ncl 78 154 4 4 4 4	My 79 177 2 6 5	Pic 80 7462 4 9 9 9	81 27 4 4 4 4	82 44 2 3 3 3	83 132 6 6 6 6	84 ⁷⁸ 6 6 6	N 85 306 5 5 5 5	/ho 86 353 6 7 6 6	Ha 87 472 6 6 6	sN 88 50 5 5 5 5	1yS 89 217 6 6 6 6	tuf 90 7679 6 7 7 7 7	f 9149 5 5 5 5	92 231 6 6 6 6 6

We have shown the length of the crash traces after reduction by each technique in Table 5. For each trace, we show its number, the original length of the crash trace before reduction and the length of the reduced crash trace for DD, HDD, BHDD, and LHDD, each in one row. Since there are too many traces (92 in total) to be shown, we have to wrap around the results at number 47 within the subject *DalvikExplorer*. We also listed the results of LHDD without pre-selection (LHDD-NoPre) in the last row for comparison purpose, which we will discuss when answering RQ3.

When compared with the original crash trace length, all the techniques achieve significant test case reduction rates. Except for a few outlier cases, most of these techniques achieve reduction rates of more than 90%. Furthermore, the actual length of crash traces after reduction is small for most of the cases. Thus we can answer RQ1 that the HDD techniques are effective to reduce the size of crash.

There are 3 crash traces (No. 28 and No. 40 of K9mail, No. 58 of WeightChart, in grey) where the family of HDD techniques generate larger reduced test case than DD technique. We have inspected these 3 crash traces carefully and found that this is due to the imprecise logging of application states in our enhanced Monkey. For K9mail, a popup window interferes with the current Activity; for WeightChart, a System Activity misleads our logger. We will improve our state logger in future work.

Despite these exceptional cases, the family of HDD techniques (HDD, BHDD, LHDD) in general has statistically comparable reduction effectiveness as the DD technique. We have performed *ANOVA* test to check whether the 4 different techniques (DD, HDD, BHDD, LHDD) have significant difference from each other. The *ANOVA* return a p-value more than 0.1, which cannot reject the null hypothesis at 0.05 significance level. Therefore, there is no significant difference among these 4 techniques in terms of reduction effectiveness.

2) Answering RQ2: In this section, we would like to know whether the family of HDD techniques is efficient such that

developers need not to wait for a prolonged period to get a reduced test case.

The test case reduction time for the 8 subject programs are shown in Fig. 6 to Fig. 13. Within each figure, the x-axis shows the crash traces number and the y-axis shows the test case reduction time in seconds. For some programs, the difference in reduction time between different crash traces is so big that we have to show the results in the log scale for y-axis.

We can see from the plots that in general the LHDD algorithm performs the best while the DD algorithm performs the worst. In fact, for majority of crash traces, the time saving of the LHDD technique compared to the DD technique is significant. For example, for crash trace No. 5 of *WeightChart*, DD takes 10 hours (36223 seconds) whereas LHDD takes only less than 7 minutes (413 seconds). When averaged over the 92 crash traces, HDD, BHDD, and LHDD save 4.6, 9.8, and 16 minutes over DD per trace, respectively. In total, HDD, BHDD, and LHDD save around 7, 15 and 25 hours of debugging time over DD on all 92 crash traces, respectively.

TABLE 6 SUMMARY OF TEST CASE REDUCTION EFFICIENCY

>		DD	H	HDD	BHDD					
	Count	Percentage	Count	Percentage	Count	Percentage				
HDD	55	60%	\	\	\	/				
BHDD	75	81%	71	77%	\	/				
LHDD	86	93%	84	91%	74	80%				

The reduction efficiency from DD to HDD and then to BHDD and finally LHDD appears to increase gradually. For each pair of techniques, we have computed the number and percentage of crash traces where the former uses less test case reduction time (in other words, better ">") than the later as shown in Table 6. HDD is more efficient than DD on 55 out of 92 cases. The percentage of crash traces where BHDD is more efficient than DD and HDD are 81% and 77%, respectively. LHDD is more efficient than DD, HDD, and BHDD on 93%, 91%, and 80% of the crash traces, respectively.



Fig. 12 Test Case Reduction Time for Yahtzee



Fig. 13 Test Case Reduction Time for K9mail

There are a few exception cases where LHDD is slower to perform reduction than DD. We have examined those cases to understand the reasons behind. For example, the crash trace No. 1 and No. 6 of Ringdroid optionally popped up an AlertDialog, which hided the underlying Activity. This situation made our Monkey tool unable to log the correct GUI states. Similarly, the crash trace No. 5 and No. 16 of K9mail popped ups floating windows during execution, which made our Monkey tool unable to log the same GUI states each time. This in turn disrupted the reduction process of LHDD.

Despite those exceptional cases, we can see from our results that this family of HDD techniques increasingly improves the efficiency of DD (where LHDD > BHDD > HDD > DD) without significant loss of reduction effectiveness.

3) Answering RQ3: For our LHDD algorithm, there are two optimizations to improve its performance. In this section, we would like to find out how much each optimization has contributed to the overall optimization. To perform the comparison, in the experiment, we turned off the pre-selection optimization in LHDD so that we can see the impact of each factor with comparison.

In Table 5, the rows of *LHDD-NoPre* show the reduction results of LHDD without pre-selection. We can see that in general, the reduction effectiveness of LHDD-NoPre is close to LHDD. A further ANOVA analysis also confirms that there is no significant difference between LHDD-NoPre and LHDD in terms of the size of reduced test case.

However, as shown in Fig. 6 to Fig. 13, the test case reduction time of LHDD-NoPre is larger than LHDD on most crash traces. We further count the number of crash traces where LHDD performs better than LHDD-NoPre. We found that there are 83 out of the 92 (i.e., 90%) crash traces on which LHDD performs better. Furthermore, if we compare LHDD-NoPre with its base technique BHDD (note their *partition()* routine is the same), there are 60 out of the 92 (i.e., 65%) crash traces on which

LHDD-NoPre outperforms. This result shows the performance of LHDD-NoPre lies in between BHDD and LHDD. Therefore, we can answer RQ3 that both optimizations (local reduction and pre-selection) contribute to the performance improvement of LHDD.

F. Threats to Validity

We focused on improving the efficiency of test case reduction technique rather than dealing with the impact of nondeterminism in execution. Therefore, we selected stable crash traces to perform test case reduction. We leave the handling of non-deterministic crash traces as a future work.

The definition of state equivalence also has an impact on the test case reduction. Currently, our trace representation uses the Activity ID to represent the GUI state, which is a lightweight solution. Using a finer level of GUI state equivalence to build the GUI hierarchy tree may lead to different test case reduction results. However, the logging of state will also become expensive. We will leave the exploration of this trade-off in future work.

We use Java to realize our SimplyDroid tool. We have carefully performed code review and testing on our implementation to ensure their correctness. We used 8 subjects and 92 crash traces to evaluate our SimplyDroid platform. Additional studies on more real-life crash traces will further strengthen the validity of our study.

In our experiment, we removed *Sanity* and its 7 crash traces because replaying it stably requires resetting its data before each execution. To enhance the applicability of SimplyDroid, we may perform reinstallation of the application or reload a system snapshot with the emulator before each execution.

V. RELATED WORK

In this section, we will briefly review related works, including debugging techniques, Android testing techniques, and test case reduction techniques.

A. Debugging Techniques

Fault localization is a time consuming. Program slicing [11][14][23][28] can confine the search range to a program slice instead of the entire program. A program slice can be obtained statically [24] or dynamically [1]. Spectrum-based fault localization correlates failures against problem spectra [13][21][22], which provides correlation information on program entities for users to review.

There are other techniques for fault localization, such as statistical methods to locate bugs with instrumented predicates [16], state-based methods that use variables and values, and even machine learning-based techniques that train neural networks to construct models for fault localization [4][5].

B. Android Application Testing Technique

There are also many techniques proposed for Android application testing.

Model based testing techniques first build a model for the application under test and then generate test cases based on the model [10]. Amalfitano et al. [2] proposed a crawler-based technique to build a GUI model and generate input events. PUMA [12] is a dynamic analysis framework and test case generation tool with generic design. Choi et al [7] proposed the SwiftHand tool to minimize the number of application restart during testing. Azim et al. [3] proposed the A3E tool with two complementary GUI traversal strategies: A3E-Depth-First and A3E-Targeted.

Monkey is a well-known Android application random testing tool developed by Google and has been widely adopted in stress testing and reliability testing [40]. Dynodroid is another automated testing tool with strategy similar to Monkey, yet with more sophisticated strategies [17]. Sapienz is a multi-objective and search-based Android application-testing tool whose optimization goal includes both code coverage rate and fault detection rate [18].

There are also several test development platforms, such as MonkeyRunner [36], Robotium [37], and UIAutoMator [29], for developers to write customized test scripts.

C. Test Case Reduction

The goal of test case reduction or minimization is to find a minimal subset of inputs that can still produce the same failure.

Delta Debugging [25] is a method to automate the debugging of programs using the hypothesis-trial-result loop [32]. Simplification and isolation are two major algorithms of Delta Debugging [27]. DDMIN is direct realization of simplification algorithm [27], whose goal is to find a minimal subset of inputs that each element of it is necessary for reproducing the failure so that it cannot be removed.

For test case reduction of Android application, Clapp et al. [9] proposed the Non-Deterministic Delta Debugging Minimization (ND3MIN) algorithm. ND3MIN improved the DDMIN algorithm by handling the non-deterministic execution of Android input event sequence. It adopts a probability approach by executing each candidate reduction many times and only considers this candidate successful if its success rate exceeds a threshold. Our SimplyDroid tool differs from

ND3MIN in two aspects. First, they have different reduction goals. SimplyDroid tries to reproduce a crash or failure while ND3MIN tries to find a minimal event trace that can reach a given target Activity. Second, SimplyDroid mainly addresses the problem of test case reduction efficiency, whereas ND3MIN mainly addresses the problem of non-deterministic execution.

D. Simplification of Test Case with Structures

DDMIN is based on test cases of string input so that the minimal independent element of simplification is a single character. Based on DDMIN, the Berkeley Delta algorithm [31] uses a line of text as the basic unit in reduction. C-Reducer can simplify large C programs [30]. It shares the same basic idea with Delta Debugging, but uses a modularized strategy of deletion and simplification based on the grammar tree representation of the program source code [20].

Apart from C/C++ programs, there are also many test cases artifacts with explicit hierarchical structure characteristics such as HTML and XML files. Misherghi and Su proposed the original Hierarchical Delta Debugging algorithm to realize the simplification of C/C++ programs and HTML/XML files [19]. Utilizing the hierarchical structure information of the test input, their hierarchical delta debugging algorithm can be much more efficient than the standard DD algorithm.

VI. CONCLUSION AND FUTURE WORK

There are many automated test case generation techniques to ensure the quality of Android applications. The Monkey fuzz testing tool and its improved versions are simple, effective and widely adopted in the industry. The test cases generated by Monkey often contain a large number of input events, which are difficult to be used by developers in debugging. It is desirable to simplify the input event sequence as small as possible while triggering the same failure. However, the traditional delta debugging technique is slow to perform such simplification. We observe that the events within a failure-inducing trace have hierarchical relationships in the form of user interaction sessions that can be reduced together with high probability. In this work, we have proposed SimplyDroid, a crash trace simplification tool for Android applications. We have proposed a novel GUI state hierarchy tree as trace representation and a family of 3 hierarchical delta debugging algorithms to operate on this trace representation. Our experiments on 92 crash input traces on eight real-life Android applications show that techniques in this family are increasingly more efficient to perform test input reduction.

For future work, we will further study the non-deterministic execution problem in the context test case reduction. We will also perform empirical study to explore the impact of state equivalence on test case reduction.

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